

Velocity calibration and wavefield decomposition for walkover VSP data

Markus von Steht and Jürgen Mann

Wave Inversion Technology Consortium
Geophysical Institute, University of Karlsruhe (TH)



November 13, 2008

Overview

Theory

- CRS stack for VSP
- FO CRS-Operator
- Calibration method

Data example

- Survey description
- Velocity calibration
- Decomposition

Conclusions & outlook



Overview

Theory

CRS approach for VSP geometry
FO CRS traveltimes approximation
Calibration method

Data example

Survey description
Velocity calibration
Wavefield decomposition

Conclusions & outlook

Overview

Theory

CRS stack for VSP
FO CRS-Operator
Calibration method

Data example

Survey description
Velocity calibration
Decomposition

Conclusions & outlook



CRS approach for VSP geometry

Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



CRS approach for VSP geometry

Finite-offset (FO) 2D CRS stack theory initially introduced for surface seismic (Zhang et al., 2001)

Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



CRS approach for VSP geometry

Finite-offset (FO) 2D CRS stack theory initially introduced for surface seismic (Zhang et al., 2001)

- ▶ second order approximation based on paraxial ray-theory

Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



CRS approach for VSP geometry

Finite-offset (FO) 2D CRS stack theory initially introduced for surface seismic (Zhang et al., 2001)

- ▶ second order approximation based on paraxial ray-theory
- ▶ central ray is non-zero offset

Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



CRS approach for VSP geometry

Finite-offset (FO) 2D CRS stack theory initially introduced for surface seismic (Zhang et al., 2001)

- ▶ second order approximation based on paraxial ray-theory
- ▶ central ray is non-zero offset
 - ↳ expansion points (\vec{x}_S , \vec{x}_G) for each simulated source and receiver pair

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



CRS approach for VSP geometry

Finite-offset (FO) 2D CRS stack theory initially introduced for surface seismic (Zhang et al., 2001)

- ▶ second order approximation based on paraxial ray-theory
- ▶ central ray is non-zero offset
 - ↳ expansion points (\vec{x}_S , \vec{x}_G) for each simulated source and receiver pair
- ▶ FO CRS operator depends on five parameters

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



CRS approach for VSP geometry

Finite-offset (FO) 2D CRS stack theory initially introduced for surface seismic (Zhang et al., 2001)

- ▶ second order approximation based on paraxial ray-theory
- ▶ central ray is non-zero offset
 - ↳ expansion points (\vec{x}_S , \vec{x}_G) for each simulated source and receiver pair
- ▶ FO CRS operator depends on five parameters
 - ↳ multi-dimensional optimization problem

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



CRS approach for VSP geometry

Finite-offset (FO) 2D CRS stack theory initially introduced for surface seismic (Zhang et al., 2001)

- ▶ second order approximation based on paraxial ray-theory
- ▶ central ray is non-zero offset
 - ↳ expansion points (\vec{x}_S , \vec{x}_G) for each simulated source and receiver pair
- ▶ FO CRS operator depends on five parameters
 - ↳ multi-dimensional optimization problem
- ▶ geometrical explanation of stacking parameters

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



CRS approach for VSP geometry

Finite-offset (FO) 2D CRS stack theory initially introduced for surface seismic (Zhang et al., 2001)

- ▶ second order approximation based on paraxial ray-theory
- ▶ central ray is non-zero offset
 - ↳ expansion points (\vec{x}_S , \vec{x}_G) for each simulated source and receiver pair
- ▶ FO CRS operator depends on five parameters
 - ↳ multi-dimensional optimization problem
- ▶ geometrical explanation of stacking parameters
 - ↳ hypothetical wavefronts, in vicinity of sources and receivers assuming:

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



CRS approach for VSP geometry

Finite-offset (FO) 2D CRS stack theory initially introduced for surface seismic (Zhang et al., 2001)

- ▶ second order approximation based on paraxial ray-theory
- ▶ central ray is non-zero offset
 - ↳ expansion points (\vec{x}_S , \vec{x}_G) for each simulated source and receiver pair
- ▶ FO CRS operator depends on five parameters
 - ↳ multi-dimensional optimization problem
- ▶ geometrical explanation of stacking parameters
 - ↳ hypothetical wavefronts, in vicinity of sources and receivers assuming:
 - ▶ local isotropy

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



CRS approach for VSP geometry

Finite-offset (FO) 2D CRS stack theory initially introduced for surface seismic (Zhang et al., 2001)

- ▶ second order approximation based on paraxial ray-theory
- ▶ central ray is non-zero offset
 - ↳ expansion points (\vec{x}_S , \vec{x}_G) for each simulated source and receiver pair
- ▶ FO CRS operator depends on five parameters
 - ↳ multi-dimensional optimization problem
- ▶ geometrical explanation of stacking parameters
 - ↳ hypothetical wavefronts, in vicinity of sources and receivers assuming:
 - ▶ local isotropy
 - ▶ local homogeneity

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



CRS approach for VSP geometry

Finite-offset (FO) 2D CRS stack theory initially introduced for surface seismic (Zhang et al., 2001)

- ▶ second order approximation based on paraxial ray-theory
- ▶ central ray is non-zero offset
 - ↳ expansion points (\vec{x}_S , \vec{x}_G) for each simulated source and receiver pair
- ▶ FO CRS operator depends on five parameters
 - ↳ multi-dimensional optimization problem
- ▶ geometrical explanation of stacking parameters
 - ↳ hypothetical wavefronts, in vicinity of sources and receivers assuming:
 - ▶ local isotropy
 - ▶ local homogeneity
 - ▶ known velocities

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



CRS approach for VSP geometry

Finite-offset (FO) 2D CRS stack theory initially introduced for surface seismic (Zhang et al., 2001)

- ▶ second order approximation based on paraxial ray-theory
- ▶ central ray is non-zero offset
 - ↳ expansion points (\vec{x}_S , \vec{x}_G) for each simulated source and receiver pair
- ▶ FO CRS operator depends on five parameters
 - ↳ multi-dimensional optimization problem
- ▶ geometrical explanation of stacking parameters
 - ↳ hypothetical wavefronts, in vicinity of sources and receivers assuming:
 - ▶ local isotropy
 - ▶ local homogeneity
 - ▶ known velocities → **calibration required**

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

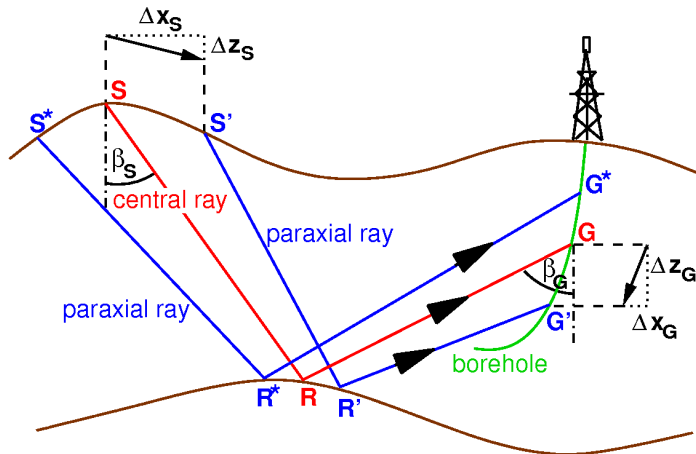
Velocity calibration

Decomposition

Conclusions & outlook



VSP measurement configuration



S and G are the positions of \vec{x}_S and \vec{x}_G , respectively

Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



CRS Operator for arbitrary geometry

CRS Operator for arbitrary geometry

$$\begin{aligned}\tau_{\text{hyp}}^2 &= \left(\tau_0 + \frac{\sin \beta_S}{v_S} \Delta x_S - \frac{\cos \beta_S}{v_S} \Delta z_S + \frac{\sin \beta_G}{v_G} \Delta x_G - \frac{\cos \beta_G}{v_G} \Delta z_G \right)^2 \\ &+ \tau_0 AB^{-1} (\Delta x_S - \Delta z_S \tan \beta_S)^2 \\ &+ \tau_0 DB^{-1} (\Delta x_G - \Delta z_G \tan \beta_G)^2 \\ &- 2 \tau_0 B^{-1} (\Delta x_S - \Delta z_S \tan \beta_S) (\Delta x_G - \Delta z_G \tan \beta_G).\end{aligned}$$

CRS Operator for arbitrary geometry

$$\begin{aligned}\tau_{\text{hyp}}^2 &= \left(\tau_0 + \frac{\sin \beta_S}{v_S} \Delta x_S - \frac{\cos \beta_S}{v_S} \Delta z_S + \frac{\sin \beta_G}{v_G} \Delta x_G - \frac{\cos \beta_G}{v_G} \Delta z_G \right)^2 \\ &+ \tau_0 AB^{-1} (\Delta x_S - \Delta z_S \tan \beta_S)^2 \\ &+ \tau_0 DB^{-1} (\Delta x_G - \Delta z_G \tan \beta_G)^2 \\ &- 2 \tau_0 B^{-1} (\Delta x_S - \Delta z_S \tan \beta_S) (\Delta x_G - \Delta z_G \tan \beta_G).\end{aligned}$$

- ▶ τ_0 : travelttime of central FO ray

CRS Operator for arbitrary geometry

$$\begin{aligned}\tau_{\text{hyp}}^2 = & \left(\tau_0 + \frac{\sin \beta_S}{v_S} \Delta x_S - \frac{\cos \beta_S}{v_S} \Delta z_S + \frac{\sin \beta_G}{v_G} \Delta x_G - \frac{\cos \beta_G}{v_G} \Delta z_G \right)^2 \\ & + \tau_0 AB^{-1} (\Delta x_S - \Delta z_S \tan \beta_S)^2 \\ & + \tau_0 DB^{-1} (\Delta x_G - \Delta z_G \tan \beta_G)^2 \\ & - 2 \tau_0 B^{-1} (\Delta x_S - \Delta z_S \tan \beta_S) (\Delta x_G - \Delta z_G \tan \beta_G).\end{aligned}$$

- ▶ τ_0 : travelttime of central FO ray
- ▶ $\Delta x_S, \Delta z_S, \Delta x_G, \Delta z_G$: horizontal and vertical offsets

CRS Operator for arbitrary geometry

$$\begin{aligned}\tau_{\text{hyp}}^2 = & \left(\tau_0 + \frac{\sin \beta_S}{v_S} \Delta x_S - \frac{\cos \beta_S}{v_S} \Delta z_S + \frac{\sin \beta_G}{v_G} \Delta x_G - \frac{\cos \beta_G}{v_G} \Delta z_G \right)^2 \\ & + \tau_0 AB^{-1} (\Delta x_S - \Delta z_S \tan \beta_S)^2 \\ & + \tau_0 DB^{-1} (\Delta x_G - \Delta z_G \tan \beta_G)^2 \\ & - 2 \tau_0 B^{-1} (\Delta x_S - \Delta z_S \tan \beta_S) (\Delta x_G - \Delta z_G \tan \beta_G).\end{aligned}$$

- ▶ τ_0 : travelttime of central FO ray
- ▶ $\Delta x_S, \Delta z_S, \Delta x_G, \Delta z_G$: horizontal and vertical offsets
- ▶ v_S, v_G : velocities in the vicinity of \vec{x}_S and \vec{x}_G

CRS Operator for arbitrary geometry

$$\begin{aligned}\tau_{\text{hyp}}^2 = & \left(\tau_0 + \frac{\sin \beta_S}{v_S} \Delta x_S - \frac{\cos \beta_S}{v_S} \Delta z_S + \frac{\sin \beta_G}{v_G} \Delta x_G - \frac{\cos \beta_G}{v_G} \Delta z_G \right)^2 \\ & + \tau_0 AB^{-1} (\Delta x_S - \Delta z_S \tan \beta_S)^2 \\ & + \tau_0 DB^{-1} (\Delta x_G - \Delta z_G \tan \beta_G)^2 \\ & - 2 \tau_0 B^{-1} (\Delta x_S - \Delta z_S \tan \beta_S) (\Delta x_G - \Delta z_G \tan \beta_G).\end{aligned}$$

- ▶ τ_0 : travelttime of central FO ray
- ▶ $\Delta x_S, \Delta z_S, \Delta x_G, \Delta z_G$: horizontal and vertical offsets
- ▶ v_S, v_G : velocities in the vicinity of \vec{x}_S and \vec{x}_G
- ▶ β_S, β_G : emergence angles of central ray

CRS Operator for arbitrary geometry

$$\begin{aligned}\tau_{\text{hyp}}^2 = & \left(\tau_0 + \frac{\sin \beta_S}{v_S} \Delta x_S - \frac{\cos \beta_S}{v_S} \Delta z_S + \frac{\sin \beta_G}{v_G} \Delta x_G - \frac{\cos \beta_G}{v_G} \Delta z_G \right)^2 \\ & + \tau_0 AB^{-1} (\Delta x_S - \Delta z_S \tan \beta_S)^2 \\ & + \tau_0 DB^{-1} (\Delta x_G - \Delta z_G \tan \beta_G)^2 \\ & - 2 \tau_0 B^{-1} (\Delta x_S - \Delta z_S \tan \beta_S) (\Delta x_G - \Delta z_G \tan \beta_G).\end{aligned}$$

- ▶ τ_0 : travelttime of central FO ray
- ▶ $\Delta x_S, \Delta z_S, \Delta x_G, \Delta z_G$: horizontal and vertical offsets
- ▶ v_S, v_G : velocities in the vicinity of \vec{x}_S and \vec{x}_G
- ▶ β_S, β_G : emergence angles of central ray
- ▶ DB^{-1}, AB^{-1}, B^{-1} : composites of elements of ray-propagator matrix

A look at multi-coverage walkover data

Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

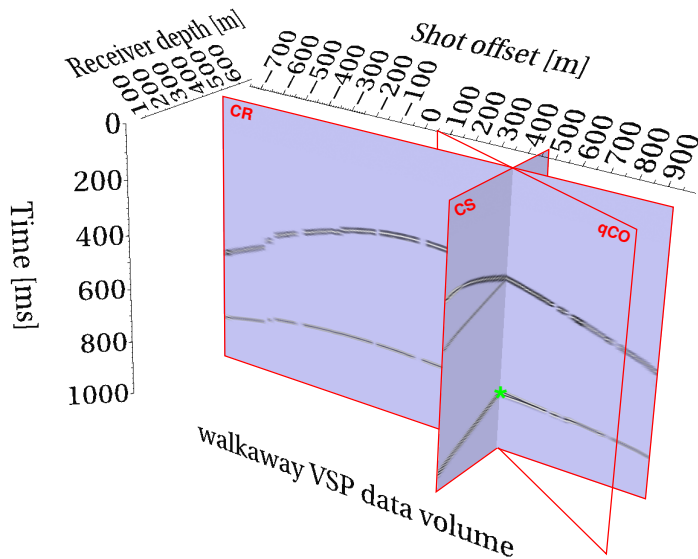
Velocity calibration

Decomposition

Conclusions & outlook



A look at multi-coverage walkover data



Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Calibration of CRS attributes

Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Calibration of CRS attributes

Stacking parameters are converted to wavefield attributes by using **tuned velocities**.

Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Calibration of CRS attributes

Stacking parameters are converted to wavefield attributes by using **tuned velocities**.

- ▶ inaccurate velocities \Leftrightarrow incorrect attributes

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Calibration of CRS attributes

Stacking parameters are converted to wavefield attributes by using **tuned velocities**.

- ▶ inaccurate velocities \Leftrightarrow incorrect attributes
- ▶ conventional way: checkshot inversion

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Calibration of CRS attributes

Stacking parameters are converted to wavefield attributes by using **tuned velocities**.

- ▶ inaccurate velocities \Leftrightarrow incorrect attributes
- ▶ conventional way: checkshot inversion often too inaccurate!

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Calibration of CRS attributes

Stacking parameters are converted to wavefield attributes by using **tuned velocities**.

- ▶ inaccurate velocities \Leftrightarrow incorrect attributes
- ▶ conventional way: checkshot inversion often too inaccurate!
- ▶ alternatively: CRS analysis of downgoing waves

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Calibration of CRS attributes

Stacking parameters are converted to wavefield attributes by using **tuned velocities**.

- ▶ inaccurate velocities \Leftrightarrow incorrect attributes
- ▶ conventional way: checkshot inversion often too inaccurate!
- ▶ alternatively: CRS analysis of downgoing waves

Assumption:



Calibration of CRS attributes

Stacking parameters are converted to wavefield attributes by using **tuned velocities**.

- ▶ inaccurate velocities \Leftrightarrow incorrect attributes
- ▶ conventional way: checkshot inversion often too inaccurate!
- ▶ alternatively: CRS analysis of downgoing waves

Assumption:

- ▶ velocities virtually constant within paraxial vicinity

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Calibration of CRS attributes

Stacking parameters are converted to wavefield attributes by using **tuned velocities**.

- ▶ inaccurate velocities \Leftrightarrow incorrect attributes
- ▶ conventional way: checkshot inversion often too inaccurate!
- ▶ alternatively: CRS analysis of downgoing waves

Assumption:

- ▶ velocities virtually constant within paraxial vicinity (already inherent assumption of CRS method)

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Calibration of CRS attributes

Stacking parameters are converted to wavefield attributes by using **tuned velocities**.

- ▶ inaccurate velocities \Leftrightarrow incorrect attributes
- ▶ conventional way: checkshot inversion often too inaccurate!
- ▶ alternatively: CRS analysis of downgoing waves

Assumption:

- ▶ velocities virtually constant within paraxial vicinity (already inherent assumption of CRS method)
 - ↳ length of slowness vector $|\vec{p}|$ independent of incidence angle

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Calibration strategy

Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Calibration strategy

- ▶ VSP data provides only one slowness component:

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Calibration strategy

- ▶ VSP data provides only one slowness component: slowness component p_t tangent to well

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Calibration strategy

- ▶ VSP data provides only one slowness component: slowness component p_t tangent to well
↳ in general insufficient to determine $|\vec{p}|$

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Calibration strategy

- ▶ VSP data provides only one slowness component: slowness component p_t tangent to well
 - ↳ in general insufficient to determine $|\vec{p}|$
- ▶ special case: walkover VSP

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Calibration strategy

- ▶ VSP data provides only one slowness component: slowness component p_t tangent to well
 - ↳ in general insufficient to determine $|\vec{p}|$
- ▶ special case: walkover VSP
 - ▶ p_t of downgoing rays varies with source position \vec{x}_S

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Calibration strategy

- ▶ VSP data provides only one slowness component: slowness component p_t tangent to well
 - ↳ in general insufficient to determine $|\vec{p}|$
- ▶ special case: walkover VSP
 - ▶ p_t of downgoing rays varies with source position \vec{x}_S
 - ▶ a ray tangent to well at receiver \vec{x}_G is very likely

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Calibration strategy

- ▶ VSP data provides only one slowness component: slowness component p_t tangent to well
 - ↳ in general insufficient to determine $|\vec{p}|$
- ▶ special case: walkover VSP
 - ▶ p_t of downgoing rays varies with source position \vec{x}_S
 - ▶ a ray tangent to well at receiver \vec{x}_G is very likely there: naturally $p_t \equiv |\vec{p}|$

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Calibration strategy

- ▶ VSP data provides only one slowness component: slowness component p_t tangent to well
 - ↳ in general insufficient to determine $|\vec{p}|$
- ▶ special case: walkover VSP
 - ▶ p_t of downgoing rays varies with source position \vec{x}_S
 - ▶ a ray tangent to well at receiver \vec{x}_G is very likely there: naturally $p_t \equiv |\vec{p}|$
- ▶ Strategy

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Calibration strategy

- ▶ VSP data provides only one slowness component: slowness component p_t tangent to well
 - ↳ in general insufficient to determine $|\vec{p}|$
- ▶ special case: walkover VSP
 - ▶ p_t of downgoing rays varies with source position \vec{x}_S
 - ▶ a ray tangent to well at receiver \vec{x}_G is very likely there: naturally $p_t \equiv |\vec{p}|$
- ▶ Strategy
 - ▶ identify downgoing direct P and/or S arrivals

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Calibration strategy

- ▶ VSP data provides only one slowness component: slowness component p_t tangent to well
 - ↳ in general insufficient to determine $|\vec{p}|$
- ▶ special case: walkover VSP
 - ▶ p_t of downgoing rays varies with source position \vec{x}_S
 - ▶ a ray tangent to well at receiver \vec{x}_G is very likely there: naturally $p_t \equiv |\vec{p}|$
- ▶ Strategy
 - ▶ identify downgoing direct P and/or S arrivals
 - ▶ calculate $p_t(\vec{x}_S, \vec{x}_G) \forall$ sources S and receivers G

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Calibration strategy

- ▶ VSP data provides only one slowness component: slowness component p_t tangent to well
 - ↳ in general insufficient to determine $|\vec{p}|$
- ▶ special case: walkover VSP
 - ▶ p_t of downgoing rays varies with source position \vec{x}_S
 - ▶ a ray tangent to well at receiver \vec{x}_G is very likely there: naturally $p_t \equiv |\vec{p}|$
- ▶ Strategy
 - ▶ identify downgoing direct P and/or S arrivals
 - ▶ calculate $p_t(\vec{x}_S, \vec{x}_G) \forall$ sources S and receivers G
 - ▶ for each G , search maximum of $p_t(\vec{x}_S, \vec{x}_G = \text{const})$

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Calibration strategy

- ▶ VSP data provides only one slowness component: slowness component p_t tangent to well
 - ↳ in general insufficient to determine $|\vec{p}|$
- ▶ special case: walkover VSP
 - ▶ p_t of downgoing rays varies with source position \vec{x}_S
 - ▶ a ray tangent to well at receiver \vec{x}_G is very likely there: naturally $p_t \equiv |\vec{p}|$
- ▶ Strategy
 - ▶ identify downgoing direct P and/or S arrivals
 - ▶ calculate $p_t(\vec{x}_S, \vec{x}_G) \forall$ sources S and receivers G
 - ▶ for each G , search maximum of $p_t(\vec{x}_S, \vec{x}_G = \text{const})$
 - ↳ searched-for velocity $v(\vec{x}_G) = \max \{p_t(\vec{x}_S; \vec{x}_G)\}^{-1}$

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



surface

well

Velocity calibration and wavefield decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

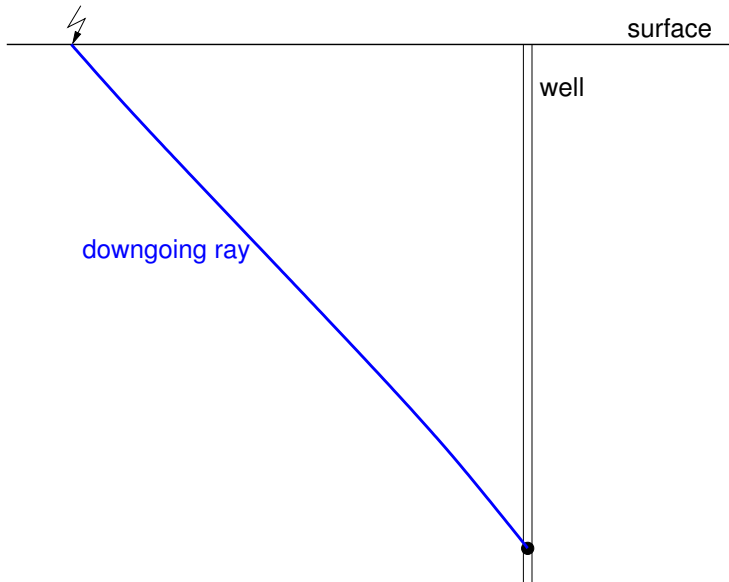
Survey description

Velocity calibration

Decomposition

Conclusions & outlook





Velocity calibration and wavefield decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

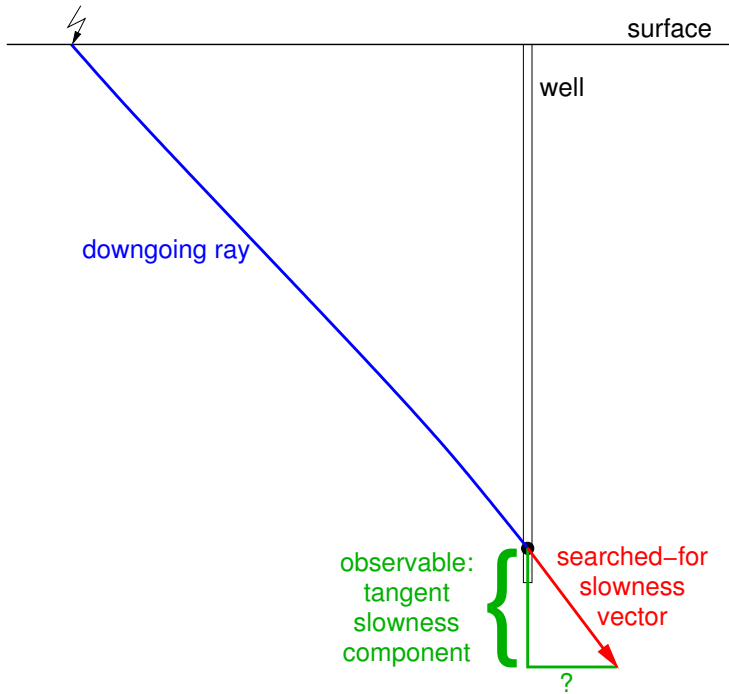
Survey description

Velocity calibration

Decomposition

Conclusions & outlook





Velocity calibration and wavefield decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

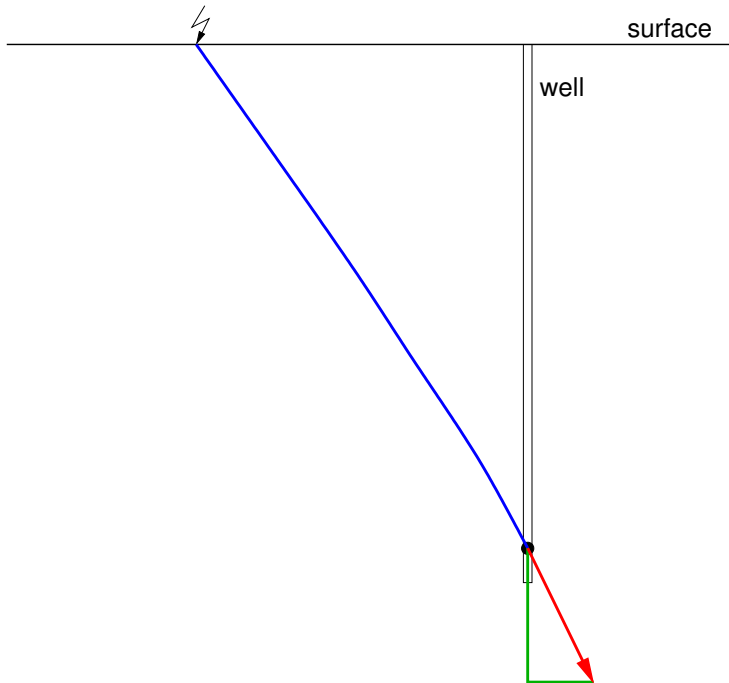
Survey description

Velocity calibration

Decomposition

Conclusions & outlook





Velocity calibration and wavefield decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

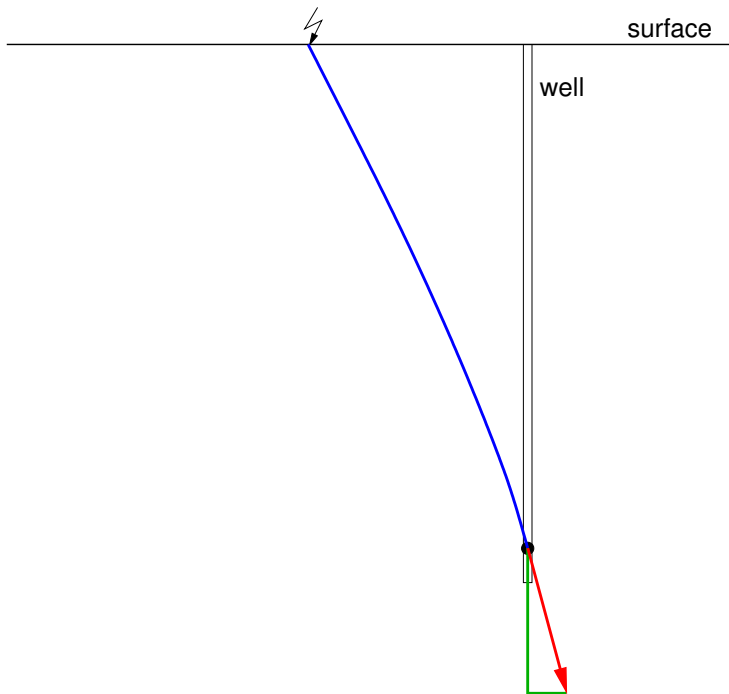
Survey description

Velocity calibration

Decomposition

Conclusions & outlook





Velocity calibration and wavefield decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

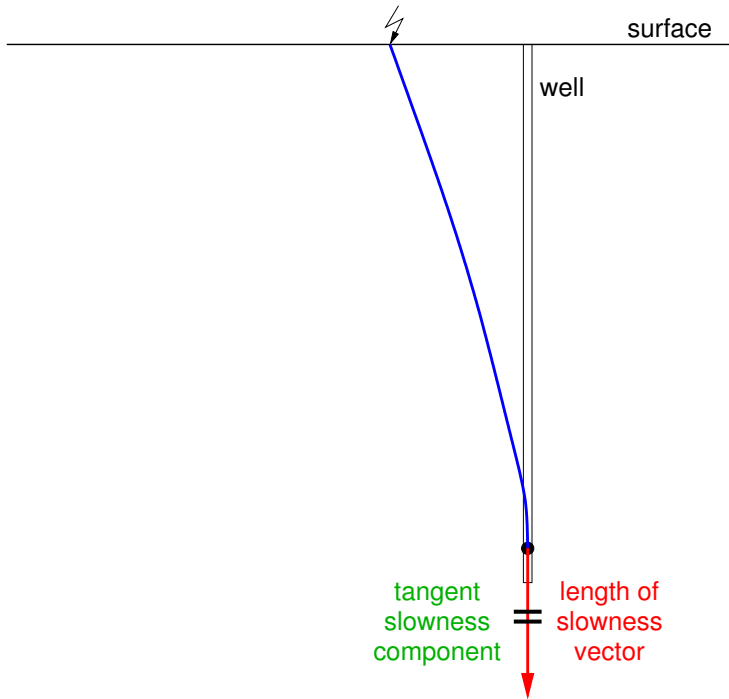
Survey description

Velocity calibration

Decomposition

Conclusions & outlook





Velocity calibration and wavefield decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

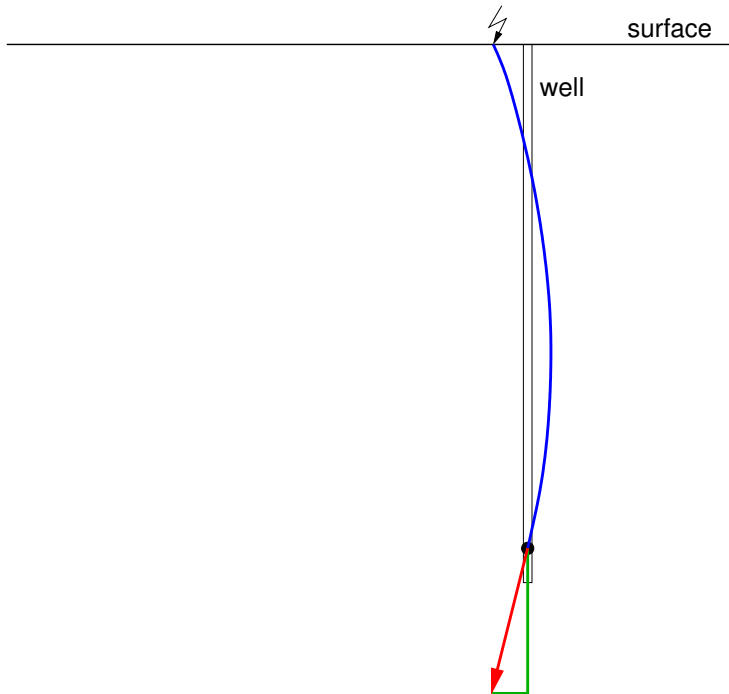
Survey description

Velocity calibration

Decomposition

Conclusions & outlook





Velocity calibration and wavefield decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Application of tuned velocities

Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Application of tuned velocities

- ▶ separate calibration for P- and S-waves

Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Application of tuned velocities

- ▶ separate calibration for P- and S-waves
- ▶ velocity v_G is property of receiver position

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Application of tuned velocities

- ▶ separate calibration for P- and S-waves
- ▶ velocity v_G is property of receiver position
 - ↳ applicable to also calibrate *reflected* waves

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Application of tuned velocities

- ▶ separate calibration for P- and S-waves
- ▶ velocity v_G is property of receiver position
 - ↳ applicable to also calibrate *reflected* waves
- ▶ Geometric interpretation provides

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Application of tuned velocities

- ▶ separate calibration for P- and S-waves
- ▶ velocity v_G is property of receiver position
 - ↳ applicable to also calibrate *reflected* waves
- ▶ Geometric interpretation provides
 - ▶ emergence angles

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Application of tuned velocities

- ▶ separate calibration for P- and S-waves
- ▶ velocity v_G is property of receiver position
 - ↳ applicable to also calibrate *reflected* waves
- ▶ Geometric interpretation provides
 - ▶ emergence angles
 - ▶ wavefront curvatures

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Application of tuned velocities

- ▶ separate calibration for P- and S-waves
- ▶ velocity v_G is property of receiver position
 - ↳ applicable to also calibrate *reflected* waves
- ▶ Geometric interpretation provides
 - ▶ emergence angles
 - ▶ wavefront curvatures
- ▶ suited for

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Application of tuned velocities

- ▶ separate calibration for P- and S-waves
- ▶ velocity v_G is property of receiver position
 - ↳ applicable to also calibrate *reflected* waves
- ▶ Geometric interpretation provides
 - ▶ emergence angles
 - ▶ wavefront curvatures
- ▶ suited for
 - ▶ wavefield decomposition

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Application of tuned velocities

- ▶ separate calibration for P- and S-waves
- ▶ velocity v_G is property of receiver position
 - ↳ applicable to also calibrate *reflected* waves
- ▶ Geometric interpretation provides
 - ▶ emergence angles
 - ▶ wavefront curvatures
- ▶ suited for
 - ▶ wavefield decomposition ➔ data example

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Application of tuned velocities

- ▶ separate calibration for P- and S-waves
- ▶ velocity v_G is property of receiver position
 - ↳ applicable to also calibrate *reflected* waves
- ▶ Geometric interpretation provides
 - ▶ emergence angles
 - ▶ wavefront curvatures
- ▶ suited for
 - ▶ wavefield decomposition ➔ data example
 - ▶ redatuming

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Application of tuned velocities

- ▶ separate calibration for P- and S-waves
- ▶ velocity v_G is property of receiver position
 - ↳ applicable to also calibrate *reflected* waves
- ▶ Geometric interpretation provides
 - ▶ emergence angles
 - ▶ wavefront curvatures
- ▶ suited for
 - ▶ wavefield decomposition ➔ data example
 - ▶ redatuming
 - ▶ inversion

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Application of tuned velocities

- ▶ separate calibration for P- and S-waves
- ▶ velocity v_G is property of receiver position
 - ↳ applicable to also calibrate *reflected* waves
- ▶ Geometric interpretation provides
 - ▶ emergence angles
 - ▶ wavefront curvatures
- ▶ suited for
 - ▶ wavefield decomposition ➔ data example
 - ▶ redatuming
 - ▶ inversion
- ▶ strategy also suited for deviated wells

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Model and survey geometry

Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

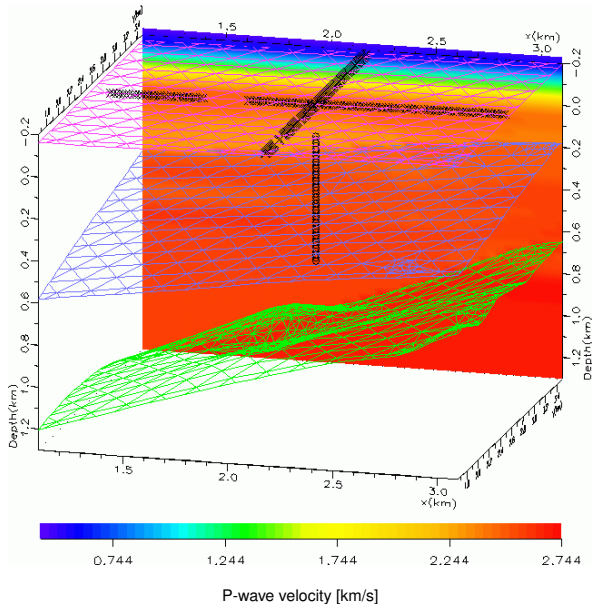
Velocity calibration

Decomposition

Conclusions & outlook



Model and survey geometry



Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP
FO CRS-Operator
Calibration method

Data example

Survey description
Velocity calibration
Decomposition

Conclusions & outlook



Model and survey geometry

Modeling:

Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Model and survey geometry

Modeling:

- ▶ wavefront construction method

Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Model and survey geometry

Modeling:

- ▶ wavefront construction method
- ▶ direct P, reflected PP & SS, converted PS

Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Model and survey geometry

Modeling:

- ▶ wavefront construction method
- ▶ direct P, reflected PP & SS, converted PS
- ▶ 3D wave propagation

Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP
FO CRS-Operator
Calibration method

Data example

Survey description
Velocity calibration
Decomposition

Conclusions & outlook



Model and survey geometry

Modeling:

- ▶ wavefront construction method
- ▶ direct P, reflected PP & SS, converted PS
- ▶ 3D wave propagation
- ▶ two walkover lines, 100 shots each

Overview

Theory

CRS stack for VSP
FO CRS-Operator
Calibration method

Data example

Survey description
Velocity calibration
Decomposition

Conclusions & outlook



Model and survey geometry

Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook

Modeling:

- ▶ wavefront construction method
- ▶ direct P, reflected PP & SS, converted PS
- ▶ 3D wave propagation
- ▶ two walkover lines, 100 shots each
- ▶ 40 three-component receiver levels



Model and survey geometry

Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook

Modeling:

- ▶ wavefront construction method
- ▶ direct P, reflected PP & SS, converted PS
- ▶ 3D wave propagation
- ▶ two walkover lines, 100 shots each
- ▶ 40 three-component receiver levels
- ▶ 2D approach sufficiently accurate for calibration



Model and survey geometry

Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Model and survey geometry

convenient CRS parameter: emergence angle

Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Model and survey geometry

convenient CRS parameter: emergence angle

↳ tangency \equiv zero angle

Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP
FO CRS-Operator
Calibration method

Data example

Survey description
Velocity calibration
Decomposition

Conclusions & outlook



Model and survey geometry

convenient CRS parameter: emergence angle

↳ tangency \equiv zero angle

Expected behavior:

Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Model and survey geometry

convenient CRS parameter: emergence angle

↳ tangency \equiv zero angle

Expected behavior:

- ▶ over-estimated velocity

Overview

Theory

CRS stack for VSP
FO CRS-Operator
Calibration method

Data example

Survey description
Velocity calibration
Decomposition

Conclusions & outlook



Model and survey geometry

convenient CRS parameter: emergence angle

↳ tangency \equiv zero angle

Expected behavior:

- ▶ over-estimated velocity
zero angle smeared over large offset range

Overview

Theory

CRS stack for VSP
FO CRS-Operator
Calibration method

Data example

Survey description
Velocity calibration
Decomposition

Conclusions & outlook



Model and survey geometry

convenient CRS parameter: emergence angle

↳ tangency \equiv zero angle

Expected behavior:

- ▶ over-estimated velocity
zero angle smeared over large offset range
- ▶ under-estimated velocity

Overview

Theory

CRS stack for VSP
FO CRS-Operator
Calibration method

Data example

Survey description
Velocity calibration
Decomposition

Conclusions & outlook



Model and survey geometry

convenient CRS parameter: emergence angle

↳ tangency \equiv zero angle

Expected behavior:

- ▶ over-estimated velocity
zero angle smeared over large offset range
- ▶ under-estimated velocity
zero angle never occurs

Overview

Theory

CRS stack for VSP
FO CRS-Operator
Calibration method

Data example

Survey description
Velocity calibration
Decomposition

Conclusions & outlook



Model and survey geometry

convenient CRS parameter: emergence angle

↳ tangency \equiv zero angle

Expected behavior:

- ▶ over-estimated velocity
zero angle smeared over large offset range
- ▶ under-estimated velocity
zero angle never occurs
- ▶ correct velocity

Overview

Theory

CRS stack for VSP
FO CRS-Operator
Calibration method

Data example

Survey description
Velocity calibration
Decomposition

Conclusions & outlook



Model and survey geometry

convenient CRS parameter: emergence angle

↳ tangency \equiv zero angle

Expected behavior:

- ▶ over-estimated velocity
zero angle smeared over large offset range
- ▶ under-estimated velocity
zero angle never occurs
- ▶ correct velocity
well-localized minimum at zero angle



Calibration using checkshot inversion

Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

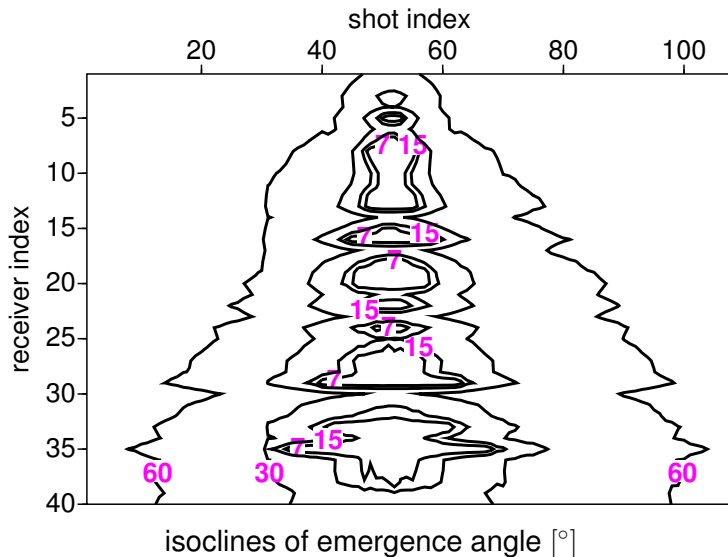
Velocity calibration

Decomposition

Conclusions & outlook



Calibration using checkshot inversion



Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

- CRS stack for VSP
- FO CRS-Operator
- Calibration method

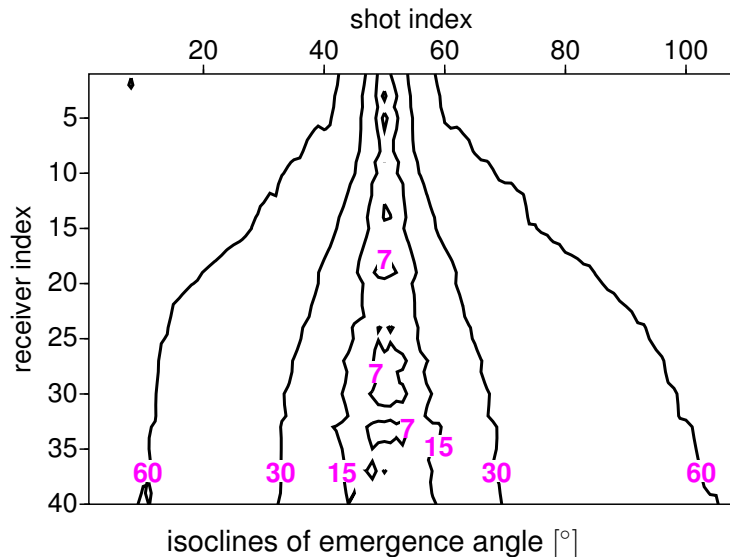
Data example

- Survey description
- Velocity calibration**
- Decomposition

Conclusions & outlook



Calibration with initial model



Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

- CRS stack for VSP
- FO CRS-Operator
- Calibration method

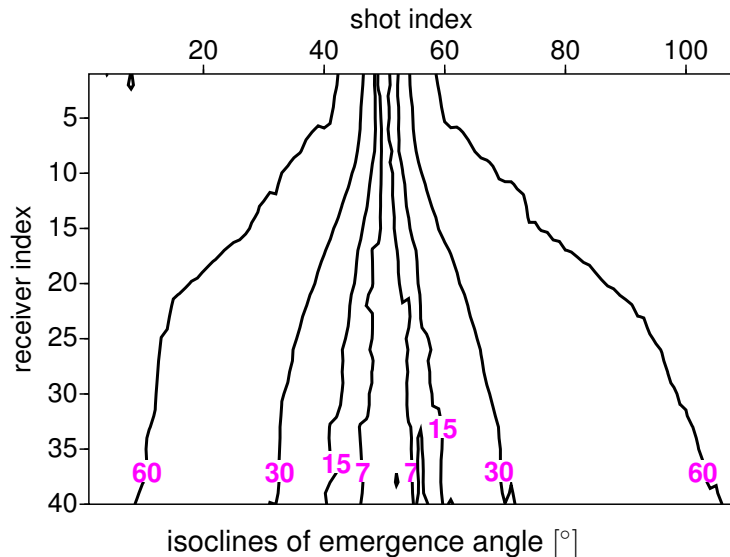
Data example

- Survey description
- Velocity calibration**
- Decomposition

Conclusions & outlook



Calibration with corrected model



Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

- CRS stack for VSP
- FO CRS-Operator
- Calibration method

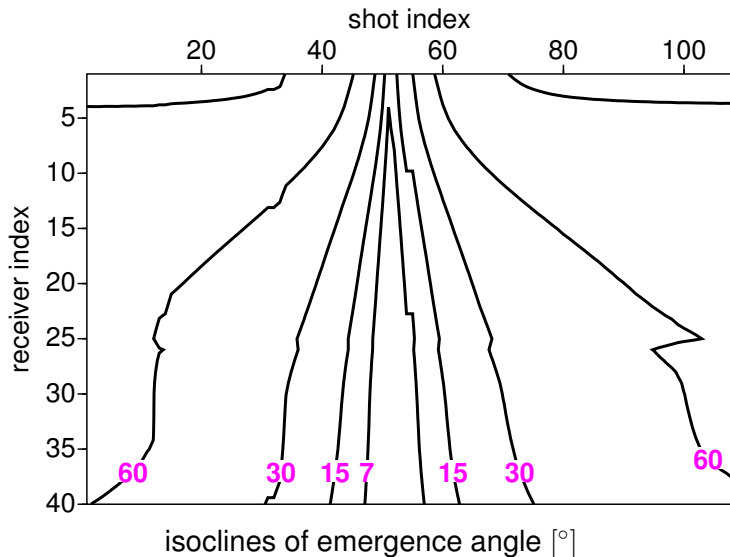
Data example

- Survey description
- Velocity calibration**
- Decomposition

Conclusions & outlook



Forward-modeled angles



Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

- CRS stack for VSP
- FO CRS-Operator
- Calibration method

Data example

- Survey description
- Velocity calibration**
- Decomposition

Conclusions & outlook



1D velocity curves along well

Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

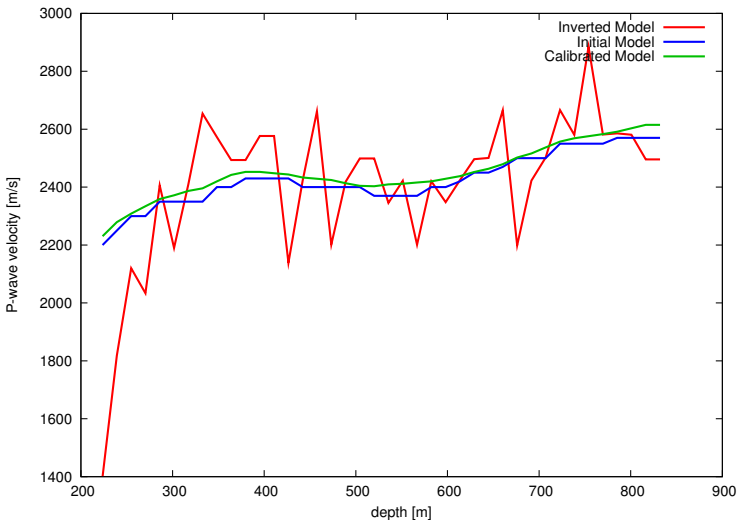
Velocity calibration

Decomposition

Conclusions & outlook



1D velocity curves along well



Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

- CRS stack for VSP
- FO CRS-Operator
- Calibration method

Data example

- Survey description
- Velocity calibration
- Decomposition

Conclusions & outlook



CRS-based wavefield decomposition

Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

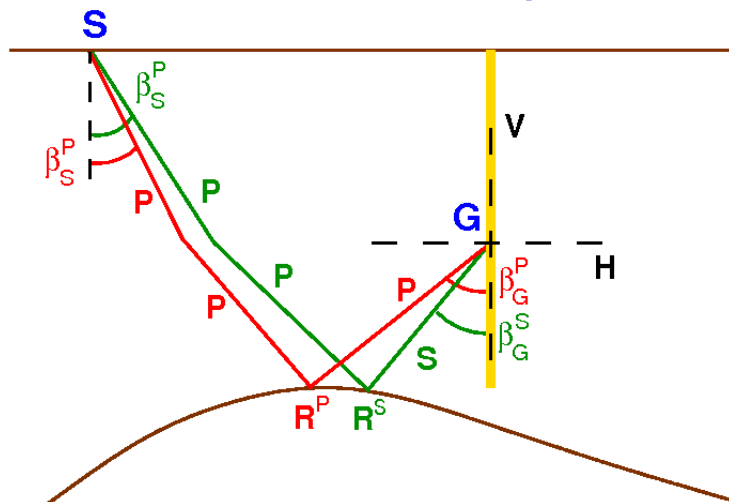
Velocity calibration

Decomposition

Conclusions & outlook



CRS-based wavefield decomposition



Components (V,H) prior to rotation

Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

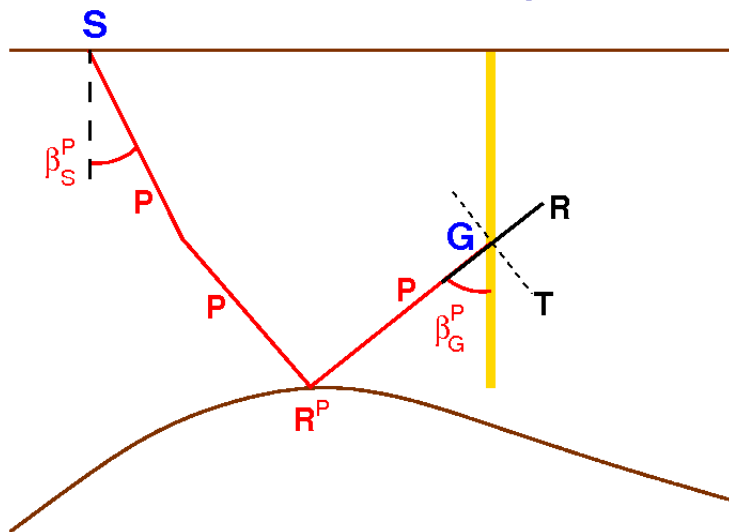
Velocity calibration

Decomposition

Conclusions & outlook



CRS-based wavefield decomposition



Components (R,T) after rotation by β_G^P – R is strong

Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

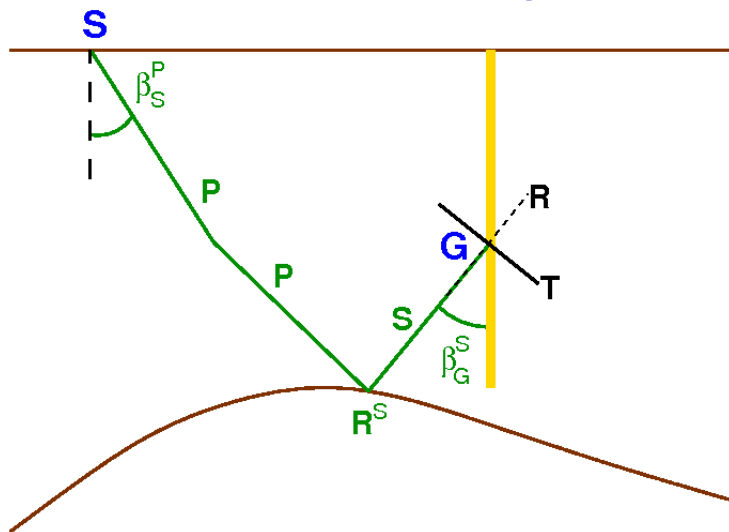
Velocity calibration

Decomposition

Conclusions & outlook



CRS-based wavefield decomposition



Components (R,T) after rotation by β_G^S – T is strong

Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

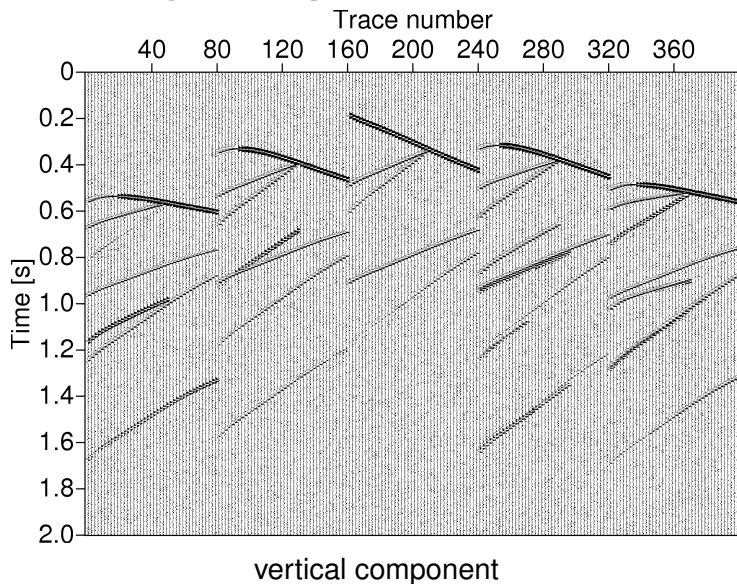
Velocity calibration

Decomposition

Conclusions & outlook



Five CS gathers prior to rotation



Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

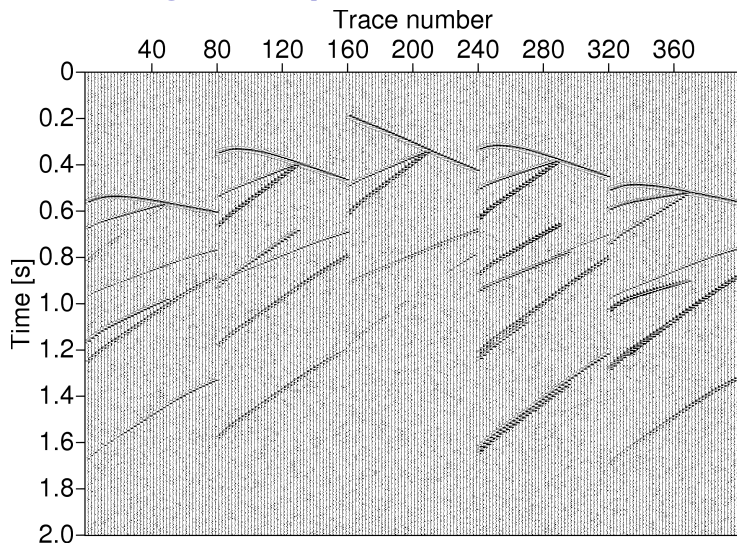
Velocity calibration

Decomposition

Conclusions & outlook



Five CS gathers prior to rotation



horizontal component

Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP
FO CRS-Operator
Calibration method

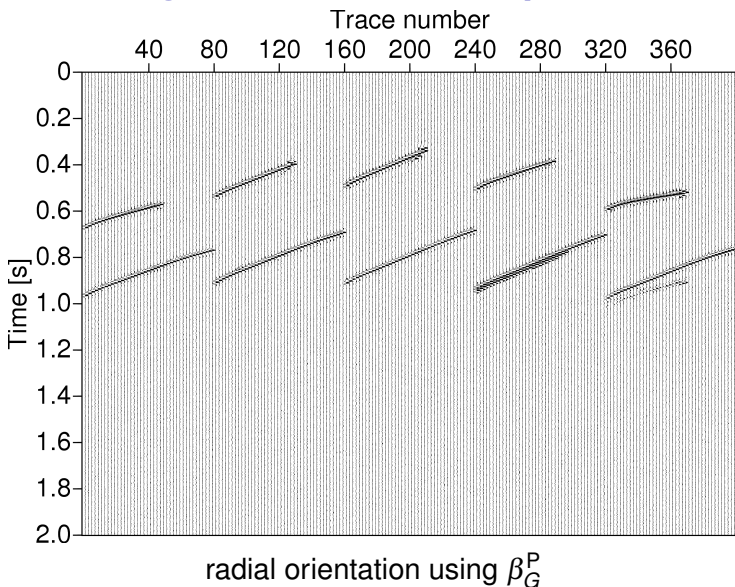
Data example

Survey description
Velocity calibration
Decomposition

Conclusions & outlook



Five CS gathers after decomposition



Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

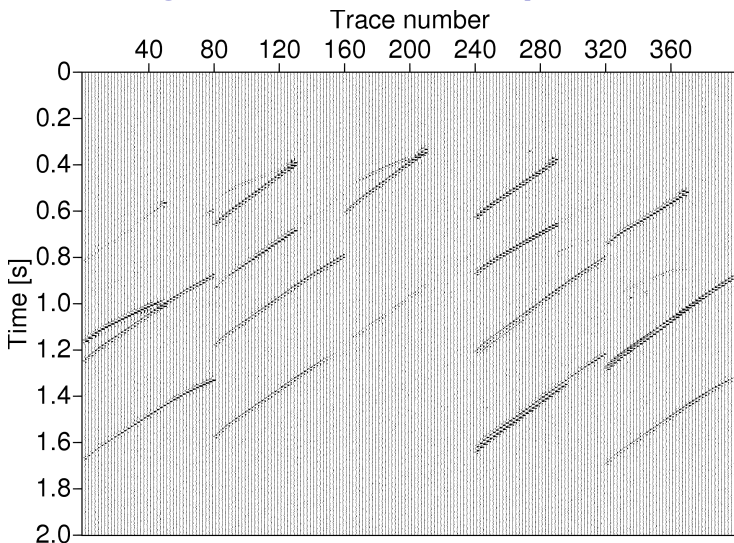
Velocity calibration

Decomposition

Conclusions & outlook



Five CS gathers after decomposition



transverse orientation using β_G^S

Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Conclusions & outlook

Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Conclusions & outlook

Calibration of CRS attributes

Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP
FO CRS-Operator
Calibration method

Data example

Survey description
Velocity calibration
Decomposition

Conclusions & outlook



Conclusions & outlook

Calibration of CRS attributes

- ▶ high sensitivity to inaccurate velocity

Overview

Theory

CRS stack for VSP
FO CRS-Operator
Calibration method

Data example

Survey description
Velocity calibration
Decomposition

Conclusions & outlook



Conclusions & outlook

Calibration of CRS attributes

- ▶ high sensitivity to inaccurate velocity
- ▶ simple criterion to determine tuned velocities

Overview

Theory

CRS stack for VSP
FO CRS-Operator
Calibration method

Data example

Survey description
Velocity calibration
Decomposition

Conclusions & outlook



Conclusions & outlook

Calibration of CRS attributes

- ▶ high sensitivity to inaccurate velocity
- ▶ simple criterion to determine tuned velocities
- ▶ readily applicable to 3D data and deviated wells

Overview

Theory

CRS stack for VSP
FO CRS-Operator
Calibration method

Data example

Survey description
Velocity calibration
Decomposition

Conclusions & outlook



Conclusions & outlook

Calibration of CRS attributes

- ▶ high sensitivity to inaccurate velocity
- ▶ simple criterion to determine tuned velocities
- ▶ readily applicable to 3D data and deviated wells
- ▶ reliable *geometrical* CRS attributes for

Overview

Theory

CRS stack for VSP
FO CRS-Operator
Calibration method

Data example

Survey description
Velocity calibration
Decomposition

Conclusions & outlook



Conclusions & outlook

Calibration of CRS attributes

- ▶ high sensitivity to inaccurate velocity
- ▶ simple criterion to determine tuned velocities
- ▶ readily applicable to 3D data and deviated wells
- ▶ reliable *geometrical* CRS attributes for
 - ▶ wavefield decomposition

Overview

Theory

CRS stack for VSP
FO CRS-Operator
Calibration method

Data example

Survey description
Velocity calibration
Decomposition

Conclusions & outlook



Conclusions & outlook

Calibration of CRS attributes

- ▶ high sensitivity to inaccurate velocity
- ▶ simple criterion to determine tuned velocities
- ▶ readily applicable to 3D data and deviated wells
- ▶ reliable *geometrical* CRS attributes for
 - ▶ wavefield decomposition
 - ▶ redatuming

Overview

Theory

CRS stack for VSP
FO CRS-Operator
Calibration method

Data example

Survey description
Velocity calibration
Decomposition

Conclusions & outlook



Conclusions & outlook

Calibration of CRS attributes

- ▶ high sensitivity to inaccurate velocity
- ▶ simple criterion to determine tuned velocities
- ▶ readily applicable to 3D data and deviated wells
- ▶ reliable *geometrical* CRS attributes for
 - ▶ wavefield decomposition
 - ▶ redatuming
 - ▶ inversion, e. g. stereo tomography

Overview

Theory

CRS stack for VSP
FO CRS-Operator
Calibration method

Data example

Survey description
Velocity calibration
Decomposition

Conclusions & outlook



Conclusions & outlook

Calibration of CRS attributes

- ▶ high sensitivity to inaccurate velocity
- ▶ simple criterion to determine tuned velocities
- ▶ readily applicable to 3D data and deviated wells
- ▶ reliable *geometrical* CRS attributes for
 - ▶ wavefield decomposition
 - ▶ redatuming
 - ▶ inversion, e. g. stereo tomography
 - ▶ ...

Overview

Theory

CRS stack for VSP
FO CRS-Operator
Calibration method

Data example

Survey description
Velocity calibration
Decomposition

Conclusions & outlook



Conclusions & outlook

Calibration of CRS attributes

- ▶ high sensitivity to inaccurate velocity
- ▶ simple criterion to determine tuned velocities
- ▶ readily applicable to 3D data and deviated wells
- ▶ reliable *geometrical* CRS attributes for
 - ▶ wavefield decomposition
 - ▶ redatuming
 - ▶ inversion, e. g. stereo tomography
 - ▶ ...
- ▶ possible combination with hodogram analysis

Overview

Theory

CRS stack for VSP
FO CRS-Operator
Calibration method

Data example

Survey description
Velocity calibration
Decomposition

Conclusions & outlook



Acknowledgments

This work was kindly supported by...

- ▶ the sponsors of the Wave Inversion Technology (WIT) Consortium
- ▶ Paulsson Geophysical Services Inc. for providing synthetic data and tremendous assistance in questions of VSP imaging

Velocity calibration
and wavefield
decomposition

M. von Steht & J. Mann

Overview

Theory

CRS stack for VSP

FO CRS-Operator

Calibration method

Data example

Survey description

Velocity calibration

Decomposition

Conclusions & outlook



Velocity calibration and wavefield decomposition

M. von Steht & J. Mann

Overview

Theory

- CRS stack for VSP
- FO CRS-Operator
- Calibration method

Data example

- Survey description
- Velocity calibration
- Decomposition

Conclusions & outlook

